

# ETF3231/5231: Business forecasting

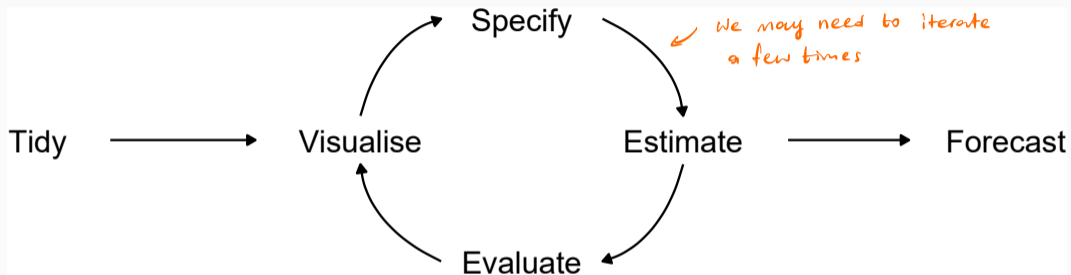
Week 4: The forecasters' toolbox  
<https://bf.numbat.space/>



- 1 A tidy forecasting workflow
- 2 Some simple forecasting methods
- 3 Time trends and seasonal dummies
- 4 Residual diagnostics
- 5 Distributional forecasts and prediction intervals
- 6 Forecasting with transformations
- 7 Forecasting and decomposition
- 8 Evaluating forecast accuracy
- 9 Time series cross-validation

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# A tidy forecasting workflow



Switch to R - demo GDP example

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## Four benchmarks

- $\text{MEAN}(y)$ : Average method
- $\text{NAIVE}(y)$ : Naïve method
- $\text{SNAIVE}(y \sim \text{lag}(m))$ : Seasonal naïve method
- $\text{RW}(y \sim \text{drift}())$ : Drift method

Note: distinguish between a method and a model

Method

Forecasts

Implicit  
model

$$\varepsilon_t \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$$

MEAN ( )

$$\hat{y}_{T+h|T} = \bar{y} = (y_1 + \dots + y_T) / T$$

NAIVE ( )

$$\hat{y}_{T+h|T} = y_T$$

SNAIVE ( )

$$\hat{y}_{T+h|T} = y_{T+h-m(k+1)}$$

DRIFT ( )

$$\begin{aligned} \hat{y}_{T+h|T} &= y_T + \frac{h}{(T-1)} \sum_{t=2}^T (y_t - y_{t-1}) \\ &= y_T + \frac{h}{T-1} (y_T - y_1) \end{aligned}$$

Method

Forecasts

Implicit

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$$\varepsilon_t \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$$

MEAN ( )

$$\hat{y}_{T+h|T} = \bar{y} = (y_1 + \dots + y_T) / T$$

$$y_t = c + \varepsilon_t$$

NAIVE ( )

$$\hat{y}_{T+h|T} = y_T$$

SNAIVE ( )

$$\hat{y}_{T+h|T} = y_{T+h-m(k+1)}$$

DRIFT ( )

$$\hat{y}_{T+h|T} = y_T + \frac{h}{(T-1)} \sum_{t=2}^T (y_t - y_{t-1})$$

$$= y_T + \frac{h}{T-1} (y_T - y_1)$$

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$$y_t = c + \varepsilon_t$$

NAIVE ( )

$$\hat{y}_{T+h|T} = y_T$$

$$y_t = y_{t-1} + \varepsilon_t$$

SNAIVE ( )

$$\hat{y}_{T+h|T} = y_{T+h-m(k+1)}$$

DRIFT ( )

$$\hat{y}_{T+h|T} = y_T + \frac{h}{(T-1)} \sum_{t=2}^T (y_t - y_{t-1})$$

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# Model fitting

- The `model()` function trains models to data.
- The `forecast()` function generates forecasts.

## SNAIVE ( $y \sim \text{lag}(m)$ ): Seasonal naïve method

- Forecasts equal to last value from same season.
- Forecasts:  $\hat{y}_{T+h|T} = y_{T+h-m(k+1)}$ , where  $m$  = seasonal period and  $k$  is the integer part of  $(h-1)/m$ .

Example: quarterly data ( $m=4$ )

$$h=2: (h-1)/m = (2-1)/4 = 0.25 \Rightarrow k=0 \text{ (integer part)}$$

$$\hat{y}_{T+2|T} = \hat{y}_{T+2-m(0+1)} = y_{T+2-4} = y_{T-2}$$



# SNAIVE ( $y \sim \text{lag}(m)$ ): Seasonal naïve method

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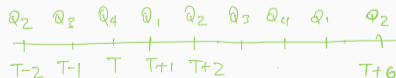
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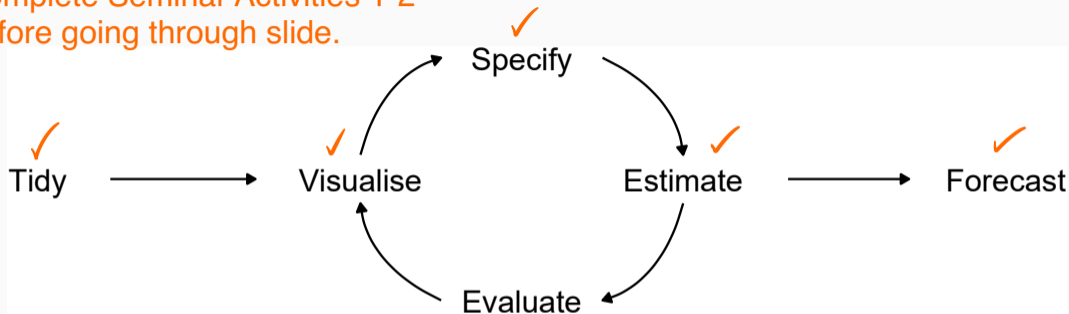
$$h=6: (h-1)/m = (6-1)/4 = 1.25 \Rightarrow k=1$$

$$\hat{y}_{T+6|T} = y_{T+6-4(1+1)} = y_{T-2}$$



# A tidy forecasting workflow - Recap

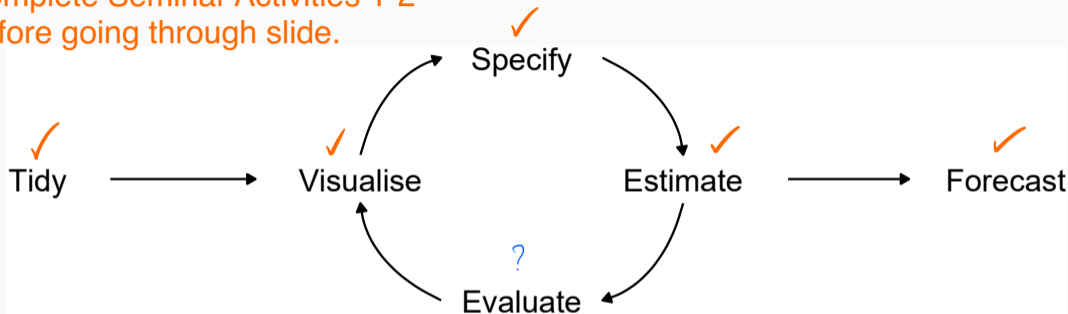
Complete Seminar Activities 1-2  
before going through slide.



• Introduced four simple methods/benchmarks (mean, naïve, seas naïve, drift)

# A tidy forecasting workflow - Recap

Complete Seminar Activities 1-2 before going through slide.



• Introduced four simple methods/benchmarks (mean, naïve, seas naïve, drift)

- Evaluate:
  1. How well do these fit the data
  2. How well do they actually forecast

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# Linear trend

$$y_t = \beta_0 + \beta_1 x_t + \varepsilon_t.$$

TSLM( $y \sim \text{trend}()$ )

- $x_t = t$ , for  $t = 1, 2, \dots, T$
- Forecasts:  $\hat{y}_{T+h|T} = \beta_0 + \beta_1(T + h)$

$$y_t = \beta_0 + \beta_1 t + \varepsilon_t$$

# Linear trend

$$y_t = \beta_0 + \beta_1 x_t + \varepsilon_t.$$

TSLM( $y \sim \text{trend}()$ )

- $x_t = t$ , for  $t = 1, 2, \dots, T$
- Forecasts:  $\hat{y}_{T+h|T} = \beta_0 + \beta_1(T + h)$

- Simple but with a strong assumption that trend will continue.
- We will see other types of trend in Week 10. *\* possibly ok for short-run*

# Daily dummy variables

TSLM( $y \sim \text{season}()$ )

- Using one dummy for each category gives too many dummy variables!
- The coefficients of the dummies are relative to the omitted category
- `season()` automatically generates the dummy variables for you.

Day	d1	d2	d3	d4
Monday	1	0	0	0
Tuesday	0	1	0	0
Wednesday	0	0	1	0
Thursday	0	0	0	1
Friday	0	0	0	0
Monday	1	0	0	0
Tuesday	0	1	0	0
Wednesday	0	0	1	0
Thursday	0	0	0	1
Friday	0	0	0	0

## Linear trend and seasonal dummies

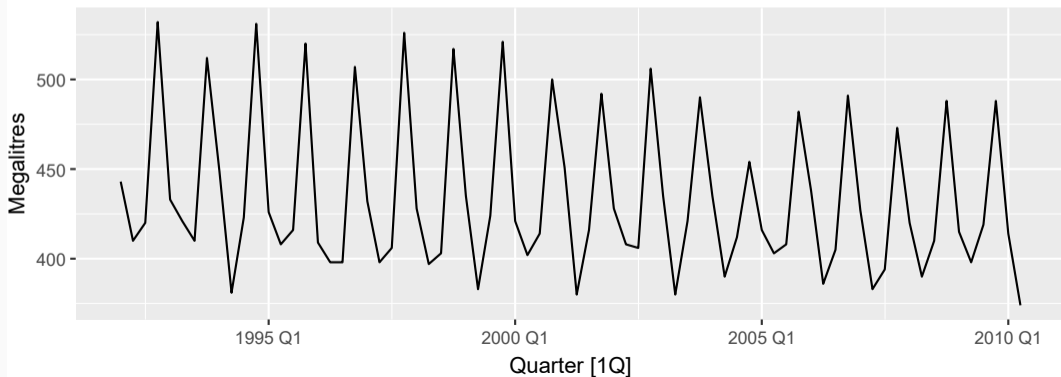
- For quarterly data: use 3 dummies
- For monthly data: use 11 dummies
- For daily data: use 6 dummies (4 for business days only)
- What to do with weekly data? (We will revisit this).

```
TSLM(y ~ trend() + season())
```

# Example: Australian quarterly beer production

```
recent_production <- aus_production |> filter(year(Quarter) >= 1992)
recent_production |>
  autoplot(Beer) +
  labs(y = "Megalitres",
       title = "Australian quarterly beer production")
```

Australian quarterly beer production



# Example: Australian quarterly beer production

```
fit_beer <- recent_production |> model(TSLM(Beer ~ trend() + season()))  
report(fit_beer)
```

Series: Beer

Model: TSLM

Residuals:

Min	1Q	Median	3Q	Max
-42.9	-7.6	-0.5	8.0	21.8

*(switch to R to  
show full  
output)*

Coefficients:

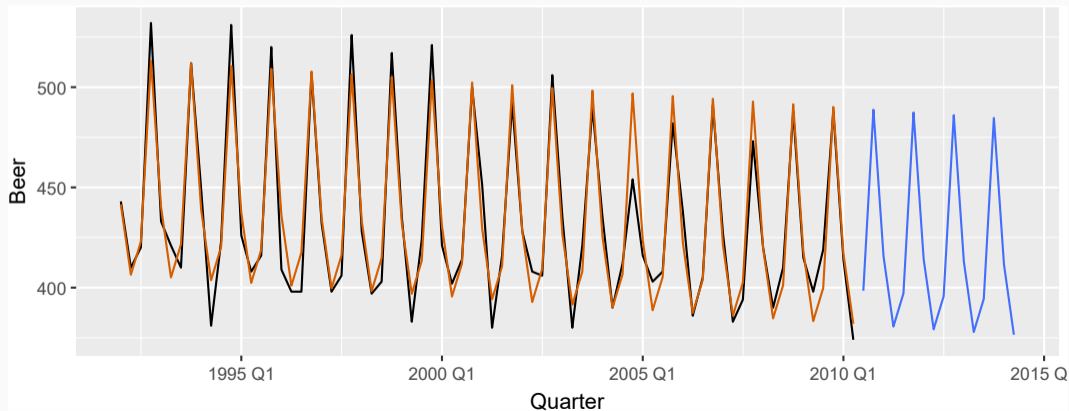
	Estimate	Std. Error	t value	Pr(> t )	
(Intercept)	441.8004	3.7335	118.33	< 2e-16	***
trend()	-0.3403	0.0666	-5.11	2.7e-06	***
season()year2	-34.6597	3.9683	-8.73	9.1e-13	***
season()year3	-17.8216	4.0225	-4.43	3.4e-05	***
season()year4	72.7964	4.0230	18.09	< 2e-16	***

---

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

# Example: Australian quarterly beer production

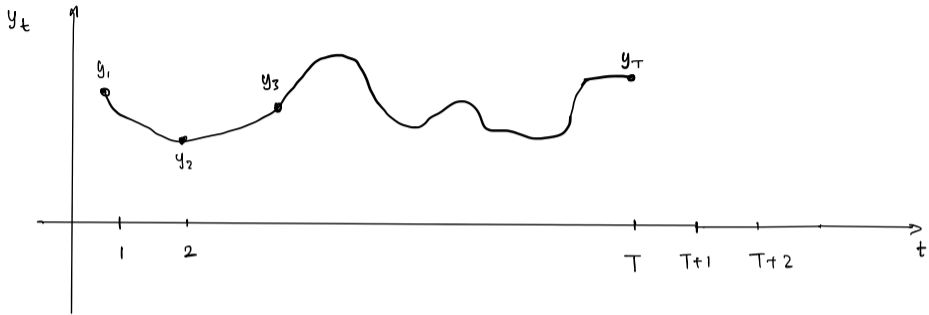
```
fit_beer |>  
  forecast(h="4 years") |>  
  autoplot(recent_production, level=NULL) +  
  autolayer(augment(fit_beer), .fitted, color='#D55E00')
```

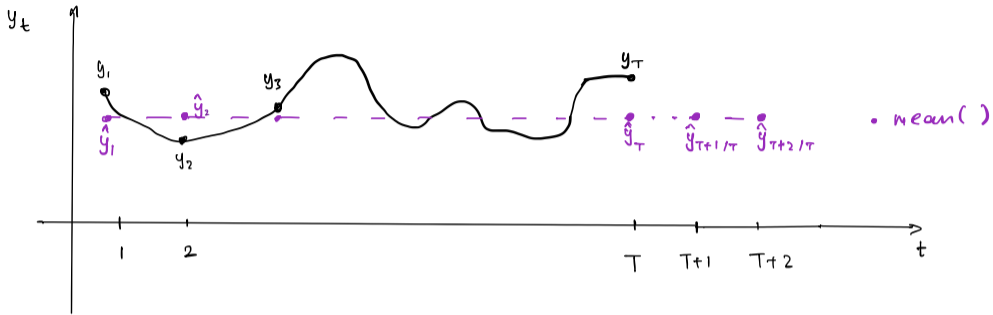


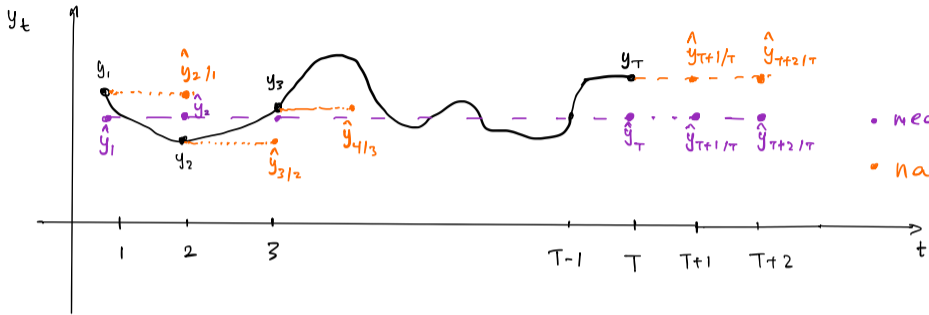
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# Forecasting residuals

**Residuals in forecasting:** difference between observed value and its fitted value:  $e_t = y_t - \hat{y}_{t|t-1}$ .







- naive()
- mean()

**Residuals in forecasting:** difference between observed value and its fitted value:  $e_t = y_t - \hat{y}_{t|t-1}$ .

## Assumptions

- 1  $\{e_t\}$  uncorrelated. If they aren't, then information left in residuals that should be used in computing forecasts.
- 2  $\{e_t\}$  have mean zero. If they don't, then forecasts are biased.

## Useful properties (for distributions & prediction intervals)

- 3  $\{e_t\}$  have constant variance.
- 4  $\{e_t\}$  are normally distributed.

# ACF of residuals

- We assume that the residuals are **white noise** (uncorrelated, mean zero, constant variance). If they aren't, then there is information left in the residuals that should be used in computing forecasts.
- So a standard residual diagnostic is to check the ACF of the residuals of a forecasting method.
- We **expect** these to look like white noise.

$$H_0: \rho_e = 0$$

# Portmanteau tests

Consider a whole set of  $r_k$  values, and develop a test to see whether the set is significantly different from a zero set.

## Ljung-Box test

$$H_0: \rho_1 = \rho_2 = \dots = \rho_\ell = 0 \sim WN$$

$$Q^* = T(T+2) \sum_{k=1}^{\ell} (T-k)^{-1} r_k^2 \sim \chi_{\ell-k}^2$$

*k = no. of parameters in the model*  
 *$\ell > k$*

where  $\ell$  is max lag being considered and  $T$  is number of observations.

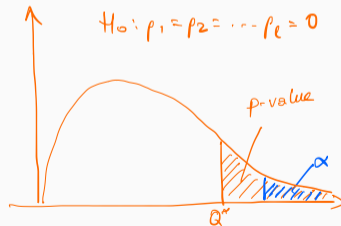
- My preferences:  $\ell = 10$  for non-seasonal data,  $\ell = 2m$  for seasonal data.
- Better performance, especially in small samples.

# Portmanteau tests

- If data are WN,  $Q^*$  has  $\chi^2$  distribution with  $(\ell - K)$  degrees of freedom where  $K = \text{no. parameters in model}$ .
- When applied to raw data, set  $K = 0$ .
- $\text{lag} = \ell, \text{dof} = K$

```
augment(fit) %>%  
  features(.resid, ljung_box, lag=10, dof=0)
```

# A tibble: 1 x 4			
Symbol	.model	$Q^*$ lb_stat	p-value lb_pvalue
<chr>	<chr>	<dbl>	<dbl>
1 FB	NAIVE(Close)	12.1	0.276



Cannot reject  $H_0$  if  $p > \alpha$ , is WN

Seminar Activities 3-4

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# Forecast distributions

Assuming residuals: have zero mean, are uncorrelated, normal, with variance =  $\hat{\sigma}^2$ :

**Mean:**  $y_{T+h|T} \sim N(\bar{y}, (1 + 1/T)\hat{\sigma}^2)$

**Naïve:**  $y_{T+h|T} \sim N(y_T, h\hat{\sigma}^2)$

**Seasonal naïve:**  $y_{T+h|T} \sim N(y_{T+h-m(k+1)}, (k+1)\hat{\sigma}^2)$

**Drift:**  $y_{T+h|T} \sim N(y_T + \frac{h}{T-1}(y_T - y_1), h\frac{T+h}{T}\hat{\sigma}^2)$

where  $k$  is the integer part of  $(h - 1)/m$ .

Note that when  $h = 1$  and  $T$  is large, these all give the same approximate forecast variance:  $\hat{\sigma}^2$ .

*So for  $h=1$  in-sample variance can be used (no need to do anything more).*

NAIVE METHOD :  $\hat{y}_{T+h|T} = y_T$

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RANDOM WALK MODEL :  $y_t = y_{t-1} + \varepsilon_t$  ,  $\varepsilon_t \sim iid N(0, \sigma^2)$   
 $t = 1, \dots, T$

NAIVE METHOD :  $\hat{y}_{T+h|T} = y_T$

RANDOM WALK MODEL :  $y_t = y_{t-1} + \varepsilon_t$  ,  $\varepsilon_t \sim iid N(0, \sigma^2)$   
 $t = 1, \dots, T$

Distinguish between residuals  $e_t = y_t - \hat{y}_{t|t-1}$  & model errors  $\varepsilon_t$

we estimate  $\sigma^2$  by  $\hat{\sigma}^2$  var of residuals

NAIVE METHOD :  $\hat{y}_{T+h|T} = y_T$

RANDOM WALK MODEL :  $y_t = y_{t-1} + \varepsilon_t$  ,  $\varepsilon_t \sim iid N(0, \sigma^2)$   
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Distinguish between residuals  $e_t = y_t - \hat{y}_{t|t-1}$  & model errors  $\varepsilon_t$

we estimate  $\sigma^2$  by  $\hat{\sigma}^2$  var of residuals

Question: What would the RW model look like at T+h? Let's do it sequentially.


$$y_t = y_{t-1} + \varepsilon_t \quad t = 1, \dots, T, \quad \varepsilon_t \sim \text{iid } N(0, \sigma^2)$$


Let's go out-of-sample/future  $t = T+1$ .

$$y_t = y_{t-1} + \varepsilon_t \quad t = 1, \dots, T, \quad \varepsilon_t \text{ iid } N(0, \sigma^2)$$

Let's go out-of-sample/future  $t = T+1$ .

$$y_{T+1} = y_T + \varepsilon_{T+1}$$


$$y_{T+2} = y_{T+1} + \varepsilon_{T+2} = y_T + \varepsilon_{T+1} + \varepsilon_{T+2}$$


$$y_{T+3} = y_{T+2} + \varepsilon_{T+3} = y_T + \varepsilon_{T+1} + \varepsilon_{T+2} + \varepsilon_{T+3}$$

⋮

$$y_{T+h} = y_T + \sum_{l=0}^h \varepsilon_{T+h-l} \quad \text{So } y_T + \text{all errors between } y_T + y_{T+h}$$

mean

$$E(y_{T+h}) = E(y_T) + \sum_{i=0}^{h-1} E(\varepsilon_{T+h-i}) = y_T$$

$$\Rightarrow \hat{y}_{T+h|T} = y_T \quad \text{a sensible model for the naive method.}$$

Variance

$$\text{var}(y_{T+h}) = \text{var}(y_T) + \sum_{i=0}^{h-1} \text{var}(\varepsilon_{T+h-i})$$

$$= 0 + (\underbrace{\sigma^2 + \sigma^2 + \dots + \sigma^2}_{h}) + \text{cov}(\quad)$$

$i=0 \quad 1 \quad \dots \quad h-1$   
 $T+h-i = T+h \quad T+h-1 \quad \dots \quad T+h-h+1$

$$\Rightarrow \text{var}(\hat{y}_{T+h|T}) = h\sigma^2 \quad (\text{notice this depends on } h)$$

HOMEWORK: derive mean & variance for the mean model

$$y_t = \mu + \varepsilon_t \quad \varepsilon_t \sim \text{iid } N(0, \sigma^2)$$

RECALL mean method

$$\hat{y}_{T+h} = \bar{y}$$

At  $T+h$   $y_{T+h} = \mu + \varepsilon_{T+h}$

mean  $E(y_{T+h}) = \mu + E(\varepsilon_{T+h}) = \mu \Rightarrow \hat{y}_{T+h|T} = \bar{y}$

which we estimate using the sample mean:  $\hat{\mu} = \frac{1}{T} \sum_{t=1}^T y_t = \bar{y}$  a sensible model for the mean method

variance  $\text{var}(y_{T+h}) = \text{var}(\mu) + \text{var}(\varepsilon_{T+h}) = \text{var}(\bar{y}) + \text{var}(\varepsilon_{T+h})$

$$\text{var}(\bar{y}) = \frac{1}{T^2} \sum_{t=1}^T \text{var}(y_t) = \frac{1}{T^2} \sum_{t=1}^T \text{var}(\mu + \varepsilon_t) = \frac{1}{T^2} \sum_{t=1}^T \text{var}(\varepsilon_t) = \frac{1}{T^2} T\sigma^2 = \frac{\sigma^2}{T}$$

$$\Rightarrow \text{var}(y_{T+h}) = \frac{\sigma^2}{T} + \sigma^2 = \sigma^2 \left(1 + \frac{1}{T}\right) \text{ (this does not depend on } h\text{)}$$

# Prediction intervals

- Assuming forecast errors are normally distributed, then a 95% PI is

$$\hat{y}_{T+h|T} \pm 1.96\hat{\sigma}_h$$

where  $\hat{\sigma}_h$  is the st dev of the  $h$ -step distribution.

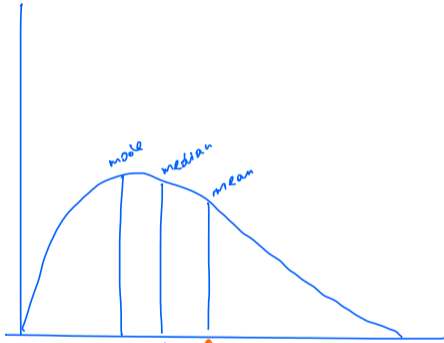
- When  $h = 1$ ,  $\hat{\sigma}_h$  can be estimated from the residuals.
- Point forecasts often useless without a measure of uncertainty (such as prediction intervals).
- Prediction intervals require a stochastic model (with random errors, etc).
- Usually too narrow due to unaccounted uncertainty. ←

## Sources of uncertainty:

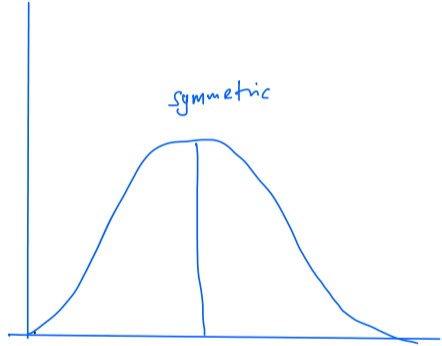
1. model errors
2. estimation uncertainty for both model & parameters
3. model choice

Seminar Activity 5

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adjust to get to the mean



- \* Please watch the video section 5.6
- \* You need to get the gist of what is happening

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# Decomposition models

`decomposition_model()` creates a decomposition model

$\hat{A}_t$

- You must provide a method for forecasting the `season_adjust` series.
- A seasonal naive method is used by default for the `seasonal` components.
- The variances from both the seasonally adjusted and seasonal forecasts are combined.

$\hat{S}_t$

Seminar Activity 6

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## SUMMARY

Train: residual diagnostics

- in-sample
- one-step
- fitted values (or forecasts)

Test: forecast evaluation

- hold-out sample (out-of-sample)
- multi-step
- forecasts

# SUMMARY

Train: residual diagnostics

- in-sample
- one-step
- fitted values (or forecasts)

How well does the model fit the data?

Test: forecast evaluation

- hold-out sample (out-of-sample)
- multi-step
- forecasts

How well does the model actually forecast?

# SUMMARY

Train: residual diagnostics

- in-sample
- one-step
- fitted values (or forecasts)

Test: forecast evaluation

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→

- evaluation versus model assumptions
  - uncorrelated
  - mean zero
  - constant variance
  - normal

iid  $N(0, \sigma^2)$

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- ↓
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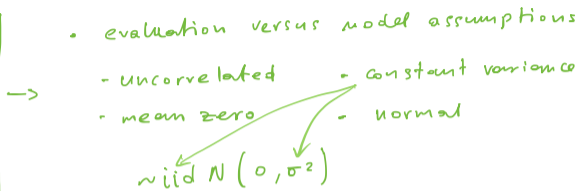
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→

• evaluation versus model assumptions

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- constant variance

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- normal

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# SUMMARY

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- in-sample
- one-step
- fitted values (or forecasts)

Test: forecast evaluation

- hold-out sample (out-of-sample)
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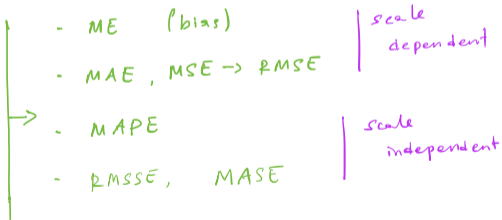
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\*

please watch the video  
Section 5-8 & read the book

\*

Seminar Activity 7-8

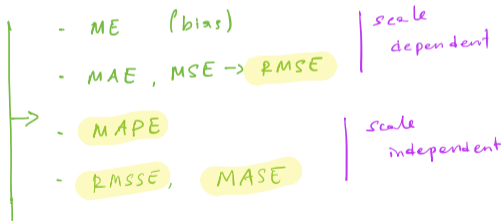
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Seminar Activity 7-8

- 1 A tidy forecasting workflow
- 2 Some simple forecasting methods
- 3 Time trends and seasonal dummies
- 4 Residual diagnostics
- 5 Distributional forecasts and prediction intervals
- 6 Forecasting with transformations
- 7 Forecasting and decomposition
- 8 Evaluating forecast accuracy
- 9 Time series cross-validation

## Creating the rolling training sets

There are three main rolling types which can be used.

- Stretch: extends a growing length window with new data.
- Slide: shifts a fixed length window through the data.
- Tile: moves a fixed length window without overlap.

Three functions to roll a tsibble: `stretch_tsibble()`, `slide_tsibble()`, and `tile_tsibble()`.

For time series cross-validation, stretching windows are most commonly used.

# Creating the rolling training sets

